

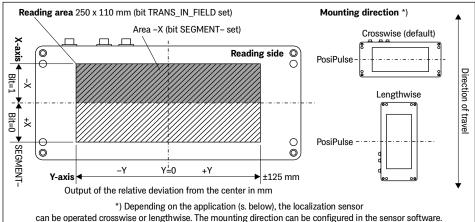


Functional Description

The RFID localization sensor HG G-98820 exclusively measures the position of a passive RFID tag (transponder) relative to the center of the sensor along the Y-axis. Depending on the application (see table below), the sensor is mounted crosswise or lengthwise to the direction of travel; the mounting direction can be configured in the sensor software. The sensor and transponder are largely insensitive to dirt and moisture and can also be used in harsh environments.

As long as a transponder is in the reading range of the sensor, the relative position information of the transponder is continuously output. Its code is also output so that it can be identified. If the absolute position of the identified transponder is known, the absolute position of the sensor can be calculated from the relative measurement. When crossing the center axis in the direction of travel (see illustration below), a high-precision positioning pulse (PosiPulse) is also output.

Definitions / Mounting Direction



Application Examples			
Localization of AGV	In these applications, the sensor is installed crosswise to the direction of travel. The PosiPulse is triggered when the long center axis (Y-axis) is crossed.		
Localization of rail vehicles (ASC, RMG)	In these applications, the sensor is installed lengthwise to the direction of travel. The PosiPulse is triggered when the short center axis (X-axis) is crossed.		
Contact-free measure- ment of the displace- ment of workpieces	Due to the high reproducible measuring accuracy and measuring rate, contact-free length measurements can be carried out between moving or displaceable workpieces lengthwise to the direction of movement.		

Main Features

- RFID localization sensor for automation applications (s. table below left)
- Direction of travel adjustable crosswise or lengthwise depending on application (see illustration)
- Indoor & Outdoor, IP 65
- Mounting side may be mounted directly on metal
- Reading distance depending on the transponder type in use 20 to 160 mm
- Max. crossing speed depending on the mounting direction 4 m/s (crosswise) respectively 6 m/s (lengthwise)
- Bus interface depending on variant CAN/CANopen® or PROFINET® (see below)
- PosiPulse when crossing the center axis in driving direction
- Serial interface serves as service interface for configuration (also for updating the antenna software) or data interface (configurable telegram contents)
- Programming of transponders

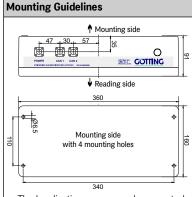
Versions/Variants				
HG G-98820	ZΒ	CAN/CANopen®		
	ZC	CAN/CANopen®, stain- less steel connectors		
		less steel connectors		
	YC	PROFINET®, stainless		
		steel connectors		

Götting Product IDs (order codes)			
HG G-98820ZC			
	Production series (no functional relevance) Functional Model / Version Identification Number / Type G: Device K: Component S: System W: Software HG: Götting HW: Resale		

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Product page: https://goetting-agv.com/components/98820





- The localization sensor can be mounted crosswise or lengthwise (see picture on the right).
- The mounting side of the sensor can be mounted directly on metal.
- No closed electrically conductive loops within 300 mm of the sensor, especially in the area of the cover.
- No metal surfaces or metallic objects closer than 50 mm.
- No interference signals in the frequency range 64 ±4 kHz from clocked motors etc.
- Depending on the power and frequency, current-carrying cables must be far enough away from the sensor so that they do not affect reception (at least 150 mm).
- RFID localization sensors with the same energy field frequency influence each other if they are installed closer than 200 mm to each other.
- Reinforcements installed close to the road surface can distort the measured transponder position.

Settings via RS 232/Bus

- Configuration of sensor and interface parameters (only via RS 232).
- Adjustment of detection thresholds to compensate for slight disturbances.
- Software update (only via RS 232).

Complementary Products		
HW CAB00001	Power: Cable PUR, 5 m, M12 elbow socket, open	
TIVV OADOOOOI	end	
HW CON00055	CAN 1: CAN Terminator, M12 plug, 5 pin, A coded	
	CAN 2: CAN-Bus cable,	
HW CAB00064	10 m, with shielding, M12	
LULI DEL 10000E	socket straight, open end	
HW DEV00095	Disc Transponder	
HW DEV00098	Reading dist. 20-50 mm	
HG G-70633ZB	Glass Transponder	
110 0 700002B	Reading dist. 50-120 mm	
HG G-70652ZC	Puck Transponder	
HG G-70653ZA	Reading dist. 50-160 mm	
HG G-71325XA	Rod Transponder	
	Reading dist. 20-80 mm	
HG G-81840ZA	Transponder Programming	
110 0-01040ZA	Device	
HG G-06150YA	Serial -> Parallel Interface	



Connection Example Vehicle PLC / Vehicle Controller / Götting Navigation Control Unit CAN or Additional Bus participants PosiPulse omputer (e.g. PC or CAN terminator PROFINET® or Laptop) Connection via Voltage Supply +UB BUS 1 or RS 232 BUS 2 + $\overline{-}$ alternatively data or service interface +UB alternatively (CAN only) RFID Localization CONTROL SOLUTIONS Sensor picture shows HG G-98820ZB (CAN) Transponder (on or within the ground)

	n Allocations, all connectors M12				
	All Variants HG G-98820ZB/ZC			HG G-98820YC	
Pin	Power	CAN 1	CAN 2	PROFINET® 1 & 2	
	5 pin, A-coded, male	5 pin, A-coded, female	5 pin, A-coded, male	4 pin, D-coded, female	
1	+UB	Not connected	Not connected	TX+	
2	PosiPulse output	+UB	+UB	RX+	
3	TxD RS 232 data output	GND	GND	TX-	
4	RxD RS 232 data input	CAN_H	CAN_H	RX-	
5	GND	CAN_L	CAN_L		
	2-0-4	1 2 5 2	2 4	1003	

Technical Data			
Work Safety	According to the German norm BGV B11 Area 1		
Dimensions	360 mm x 160 mm x 91 mm (L x W x H)		
Casing	Plastic		
Weight	approx. 3.2 kg		
Reading area	250 mm x 110 mm (L x W)		
Frequencies	Sensor: 128 kHz / Transponder: 64 kHz		
Reading distance	Depending on the transponder type, s. table "Complementary Products"		
Voltage supply +UB	18 to 36 V, nominal voltage 24 V		
Current consumption	- 370 mA @ 24 V - up to 1 A while programming Transponders		
Temperature ranges	Operation & storage: -25° to +50° C		
Protection class	IP 65		
Signal processing time	Positioning: 1 msCode reading: 8 ms		
Measuring resolution	1 mm		
Max. crossing speed depending	- Crosswise: 4 m/s		
on the mounting direction	- Lengthwise: 6 m/s		
Static positioning accuracy	±1 mm at a height of 40 mm along the Y-axis		
Connectors	 All Variants: 1x M12 5-Pin A-coded: Power (male) HG G-98820ZB/ZC: 2x M12 5-Pin A-coded: CAN 1 (female) CAN 2 (male) HG G-98820YC: 2x M12 4-Pin D-coded: PROFINET 1 & 2 (female) 		
Interfaces	 RS 232: Output with 19200, 38400 (standard) or 115200 Bd. The telegram content is configurable. Protocol "transparent" PosiPulse: 24 V, 20 mA power source, not electrically isolated CAN (HG G-98820ZB/ZC): Not electrically isolated, terminating resistor not integrated, Full CAN Basic CAN: According to ISO/DIS 11898, identifier, data rate, standard/extended frames; adjustable via serial interface CANopen®: Device Profile DS 401, Node ID and data rate adjustable via serial interface or SDOs PROFINET® (HG G-98820YC): With integrated switch 		